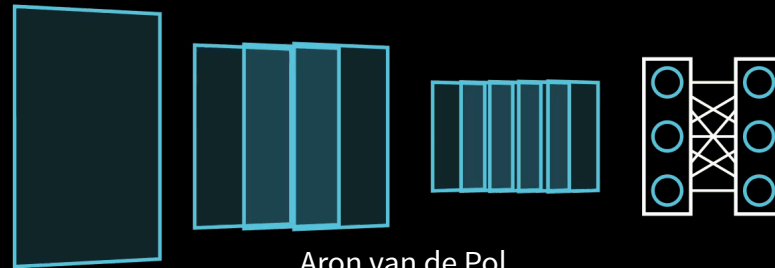


# 🔥 Deep Learning Workshop



Aron van de Pol

Leiden University Centre For Digital Humanities

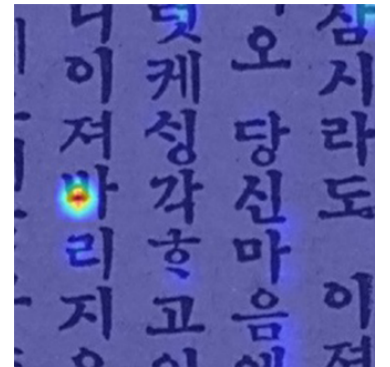
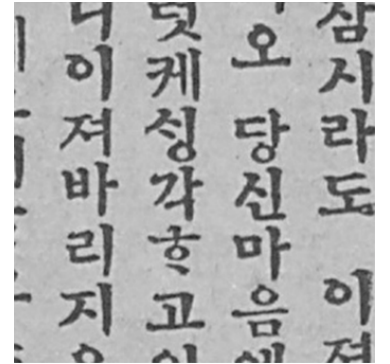
2024-02-06





# Introduction

- Aron van de Pol
- Korean Studies & Digital Humanities minor
- Focus on computer vision applications in Colonial Korean printing

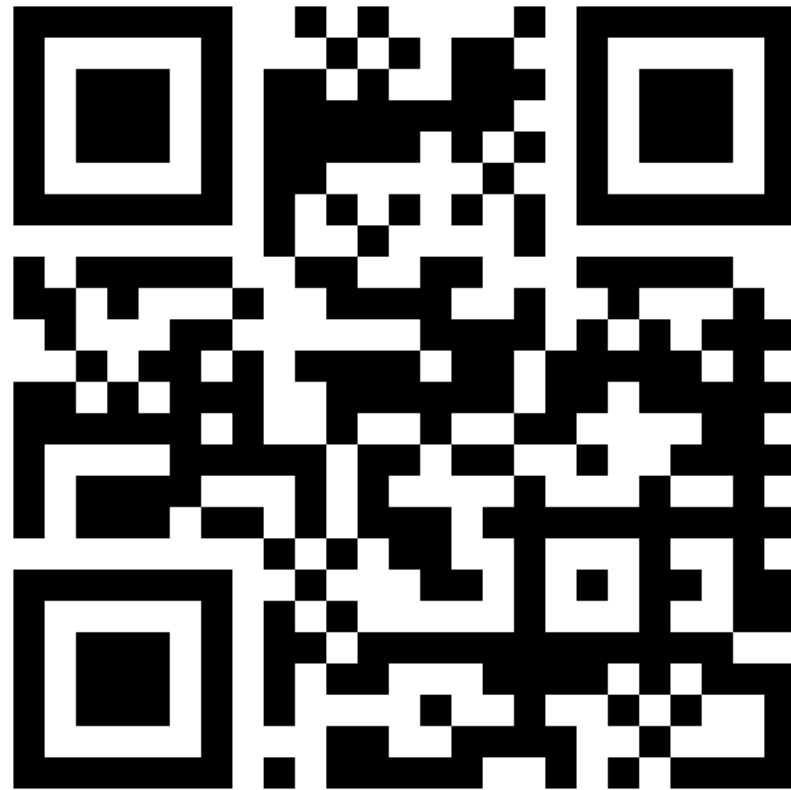




# Workshop Website

- Find all the materials and other information here:

[www.dlfh.aronvandepol.com](http://www.dlfh.aronvandepol.com)





# Planning

- **Session 1.** Tensors (6 February - **Today...**)
- **Session 2.** Linear regression (Training Pt 1.) (20 February)
- **Session 2.** Non-Linear Data (Training Pt 2. & Evaluation) (5 March)
- **Session 3.** Images as Data (19 March)
- **Session 4.** Image classification (2 April)
- **Session 5.** Transfer Learning (16 April)
- **Session 6.** Spill-over Session (30 April)



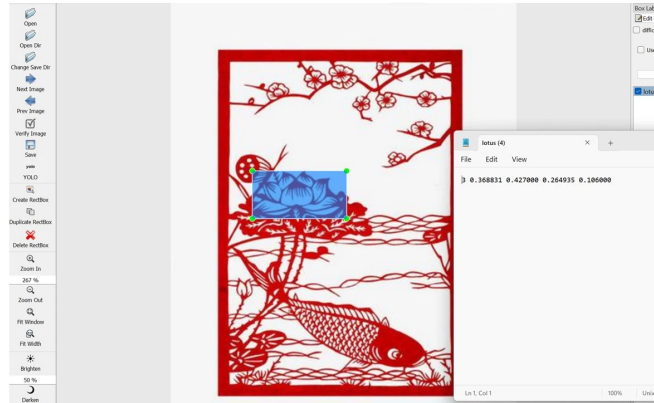


# Computer Vision?



# Computer Vision?

1. 计算机视觉的定义  
 2. 计算机视觉的应用  
 3. 计算机视觉的组成  
 4. 计算机视觉的算法  
 5. 计算机视觉的硬件  
 6. 计算机视觉的软件开发  
 7. 计算机视觉的工业应用  
 8. 计算机视觉的医学应用  
 9. 计算机视觉的军事应用  
 10. 计算机视觉的农业应用  
 11. 计算机视觉的交通应用  
 12. 计算机视觉的安防应用  
 13. 计算机视觉的娱乐应用  
 14. 计算机视觉的未来展望



- OCR/HTR
- Large Scale pattern recognition
- 3D Modelling




Top ten nearest neighbors





# Logic Networks?

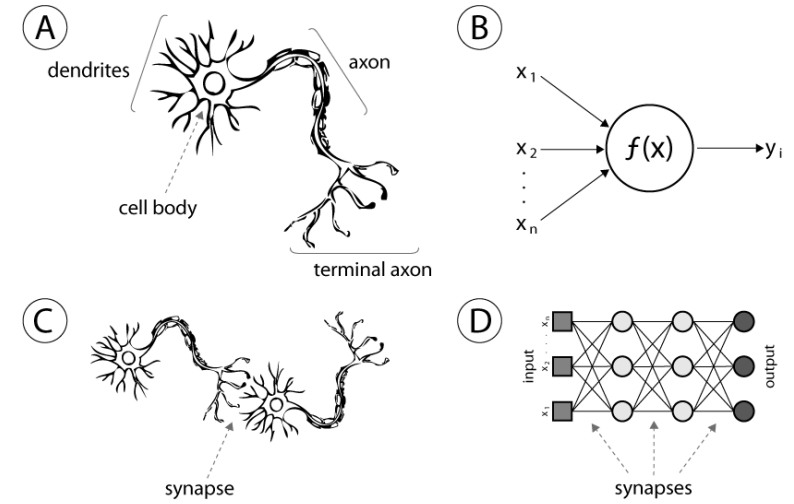
- Logic pattern approach:  $A \rightarrow B$
- *if it rains (A), I am inside (B).*
- Good for simple rules but hard for complex questions.
- How do you know that this is a cat? 
  - Whiskers?
  - Tail?
  - Ears?





# Neural Networks?

- Sometimes describing the logic is difficult
- Solution in Neural Networks
- Modeled after the human brain
- Figures out the logic by learning from examples



A Neuron & A Neuron Networks<sup>1</sup>

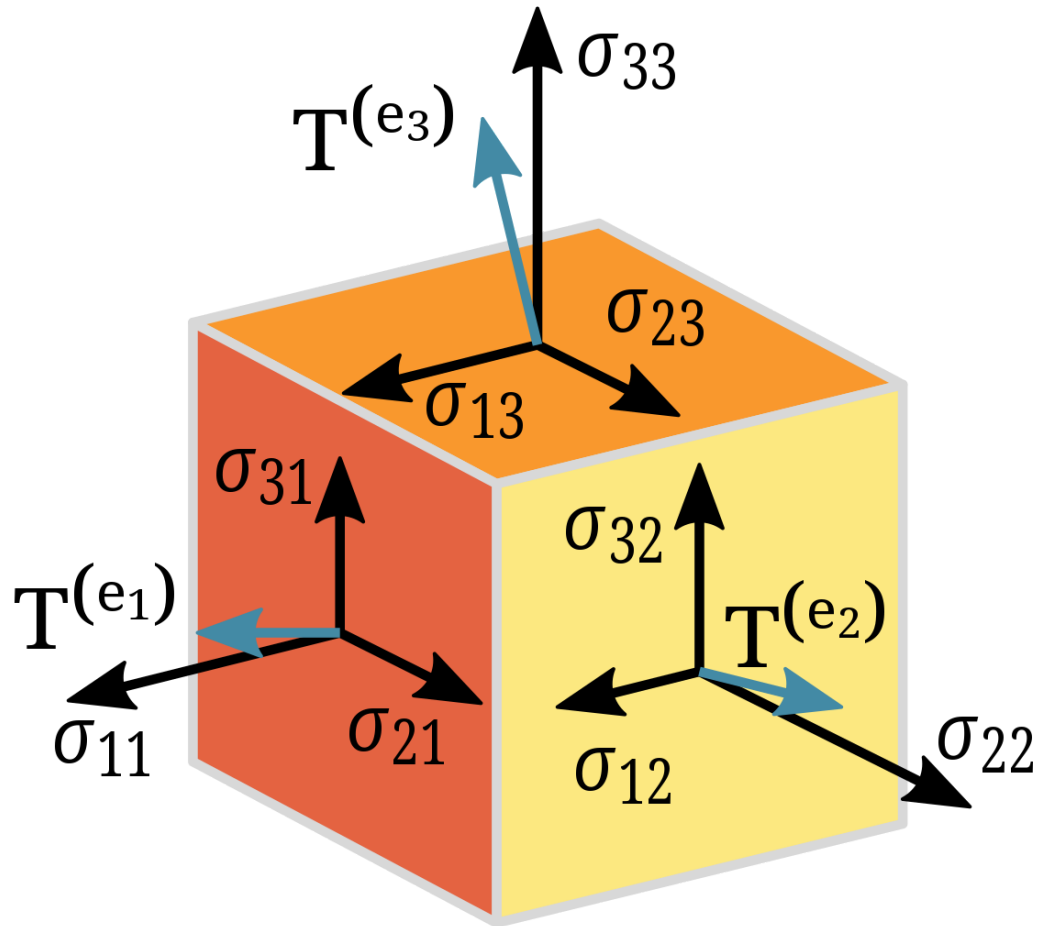






# Tensors

*The powerhouse of the Neural Network*





# Wait... Tensors?

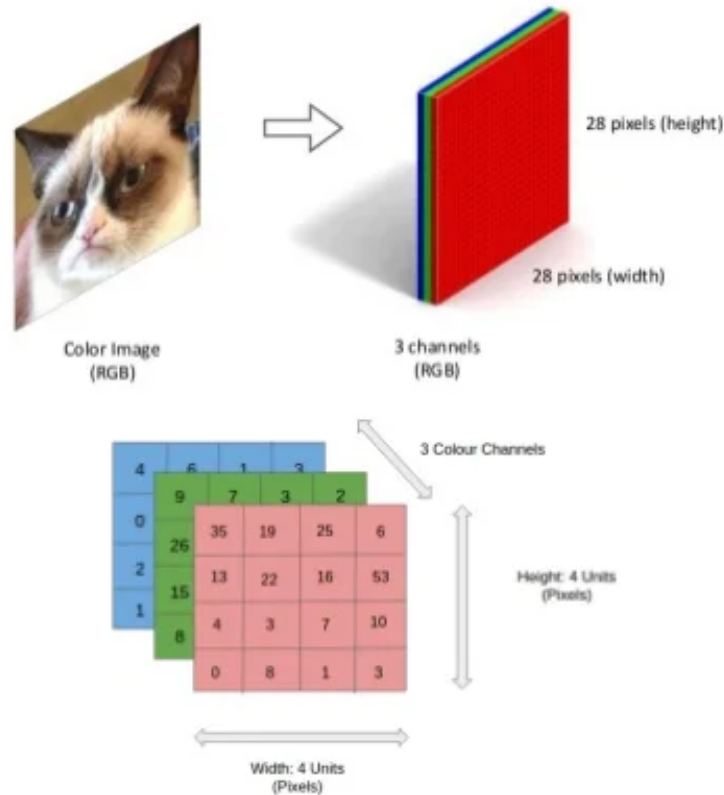
- Tensors are great at storing many types of data *efficiently*.
- Images, text, audio etc.
- Also computationally efficient.





# Okay, but what is a Tensor?

color image is 3rd-order tensor



Images from: Wikipedia contributors<sup>3</sup>, Earnshaw<sup>4</sup>, Wevers and Smits<sup>5</sup>, Wikimedia Commons contributors<sup>6</sup>



# A Scalar...

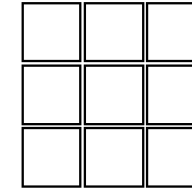
```
1 # Scalar  
2 1
```



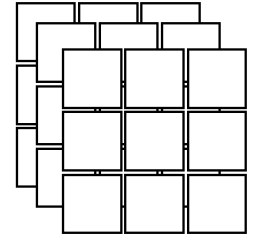
Scalar



Vector  
Tensor Rank 1



Matrix  
Tensor Rank 2



Cube  
Tensor Rank 3



# A Vector...

```
1 # Scalar  
2 1  
3  
4 # Vector  
5 [1,2,3]
```

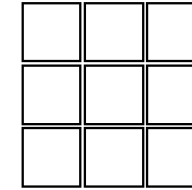


Scalar



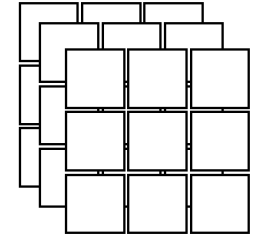
Vector

Tensor Rank 1



Matrix

Tensor Rank 2



Cube

Tensor Rank 3



# A Matrix...

```
1 # Scalar
2 1
3
4 # Vector
5 [1,2,3]
6
7 # Matrix
8 [[1,2,3],
9  [4,5,6],
10 [7,8,9]]
```

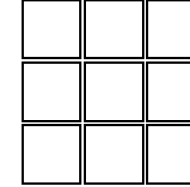


Scalar



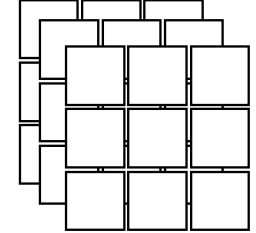
Vector

Tensor Rank 1



Matrix

Tensor Rank 2



Cube

Tensor Rank 3



# A Tensor (Cube)...

```
1 # Scalar
2 1
3
4 # Vector
5 [1,2,3]
6
7 # Matrix
8 [[1,2,3],
9  [4,5,6],
10 [7,8,9]]
11
12 # Cube
13 [[[1,2,3],
14  [4,5,6],
15  [7,8,9]],
16 [[1,2,3],
17  [4,5,6],
18  [7,8,9]]]
```

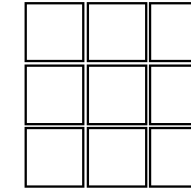


Scalar



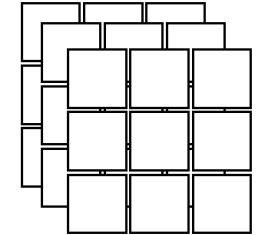
Vector

Tensor Rank 1



Matrix

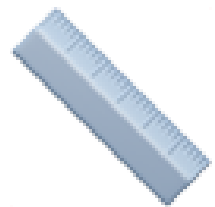
Tensor Rank 2



Cube

Tensor Rank 3





# Dimensions

*Important attributes of Tensors*







# Dimensions

- Tensors have a so-called **dimension**
- A **dimension** can be thought of as how many numbers are required to locate a point in a given tensor.

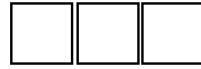




# Dimensions

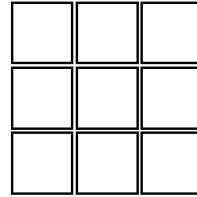


Scalar



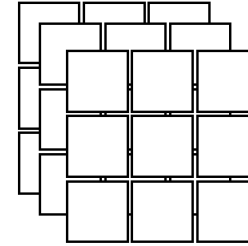
Vector

Tensor Rank 1



Matrix

Tensor Rank 2



Cube

Tensor Rank 3

- A scalar has 0 dimensions (No coordinates - only one location is possible)
- A vector has 1 dimension (One point needed)
- A matrix has 2 dimensions (Two points needed)
- A Cube-Tensor has 3 dimensions (Three points needed)

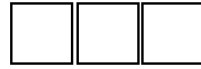




# Dimensions

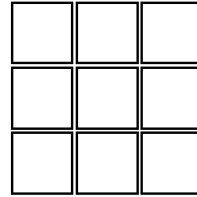


Scalar



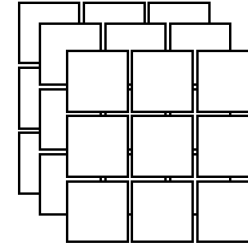
Vector

Tensor Rank 1



Matrix

Tensor Rank 2



Cube

Tensor Rank 3

Sometimes you'll encounter something like:

*N-th Dimensional Tensor*

- The N refers to the amount of dimensions of a tensor.
- An example of a useuable 4th dimensional Tensor would be colored video data. (RGB + Frame)



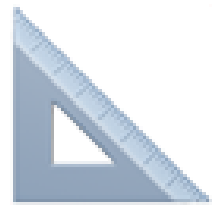


# Dimensions

Counting the number of brackets at the start will tell you the number of dimensions.

```
1 # Scalar - 0
2 1
3
4 # Vector - 1
5 [1,2,3]
6
7 # Matrix - 2
8 [[1,2,3],
9  [4,5,6],
10 [7,8,9]]
11
12 # Cube - 3
13 [[[1,2,3],
14  [4,5,6],
15  [7,8,9]],
16 [[1,2,3],
17  [4,5,6],
18  [7,8,9]]]
```





# Shapes

*Important attributes of Tensors*



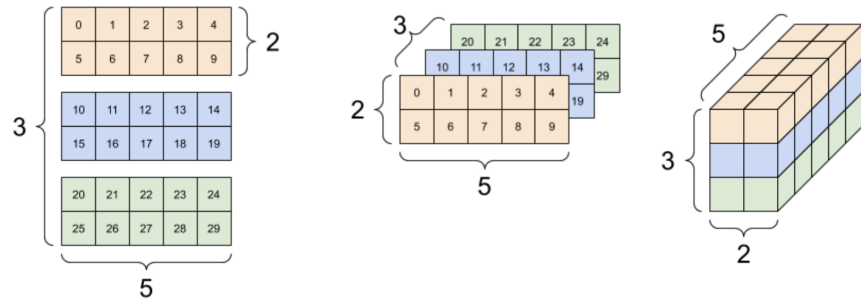
# Shapes

- Tensors also have **shapes**
- *The **shape** is the amount of elements in a tensor per **dimension**.*
- This means that:
  - A 1-D Tensor has shape  $(x)$
  - A 2-D Tensor has shape  $(x, y)$
  - A 3-D Tensor has shape  $(x, y, z)$
  - etc...



# Shapes

Take this representation of a single 3D Tensor



```
1  [[[ 0, 1, 2, 3, 4],
2   [ 5, 6, 7, 8, 9]],
3
4   [[10, 11, 12, 13, 14],
5   [15, 16, 17, 18, 19]],
6
7   [[20, 21, 22, 23, 24],
8   [25, 26, 27, 28, 29]]]
```

Its **shape** is (3,2,5).

Working from outer bracket to inner bracket.



# Why learn this?

Most issues you will encounter in while working with Neural Networks are **shape errors**.

**RuntimeError: mat1 and mat2 shapes cannot be multiplied (3x4 and 3x4)**

- Without knowing dimensions and shapes, you can not solve errors like this.
- Often as researchers we only care about the dimension and shapes of Tensors.







# Brief Test

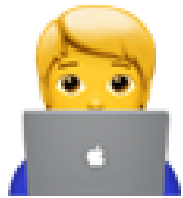
What are the # of **dimensions** and the **shape** of the following tensor?

```
1  [[[1, 2],  
2   [3, 4],  
3   [5, 6]],  
4  [[7, 8],  
5   [9, 10],  
6   [11, 12]]]
```

**dimensions: 3**

**shape: (2,3,2)**





# Let's Code

*See the website for a link to the Notebooks*





# Tensor Datatypes

- Tensors have various datatypes like other Python integers, floats or Numpy arrays.
- Some examples of common datatypes are:
  - `torch.float32`
  - `torch.float16` (half precision)
- we can find the datatype of a created `torch.tensor` using `.dtype`

```
1 X = torch.rand(1,2)
2 print(X.dtype)
3 > torch.float32
```



# Tensor Devices

- Tensors also have another attribute called **device**.
- GPUs devices are great for running many calculations in parallel.
- The possible devices are:
  - **cpu** (the processor on a computer)
  - **cuda** (The GPU on a computer)
  - **mps** (GPU on Mac computers)
  - **tpu** (Tensor Processing Units - GPUs made for tensors)



# Tensor Devices

- we can find the device of a created `torch.tensor` using `.device`

```
1 X = torch.rand(1,2)
2 print(X.device)
3 > device(type='cpu')
```

- we send tensors to devices like so:

```
1 X = torch.rand(1,2)
2 X.to('cuda')
3 print(X.device)
4 > device(type='cuda:0')
```

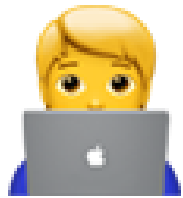


# ✗ Datatype & Device Errors

Why learn this?

- Besides the `shape error` the second most common errors are:
  - `dtype errors`
  - `device errors`
- These occur when mixing devices or types.
  - combining `torch.float32` and `torch.float16`.
  - combining `device='cpu'` and `device='gpu'`.

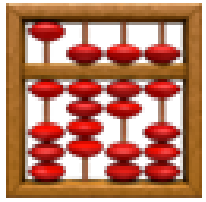




# Let's Code

*See the website for a link to the Notebooks*





# Tensor Operations







# Simple Operations

- Addition

$$1 \quad [1, 2, 3] + 2 = [3, 4, 5]$$

2

$$3 \quad [1, 2, 3] + [3, 2, 1] = [4, 4, 4]$$

- Subtraction

$$1 \quad [1, 2, 3] - 2 = [-1, 0, 1]$$

2

$$3 \quad [1, 2, 3] - [3, 2, 3] = [-2, 0, 0]$$





# Simple Operations

- Multiplication (element-wise)

```
1 [1,2,3] * 2      = [2,4,6]
2
3 [1,2,3] * [3,2,3] = [3,4,9]
```

- Division

```
1 [1,2,3] / 2      = [0.5000,1.0000,1.5000]
2
3 [1,2,3] / [3,2,3] = [0.3333,1.0000,1.0000]
```





# Matrix Multiplication

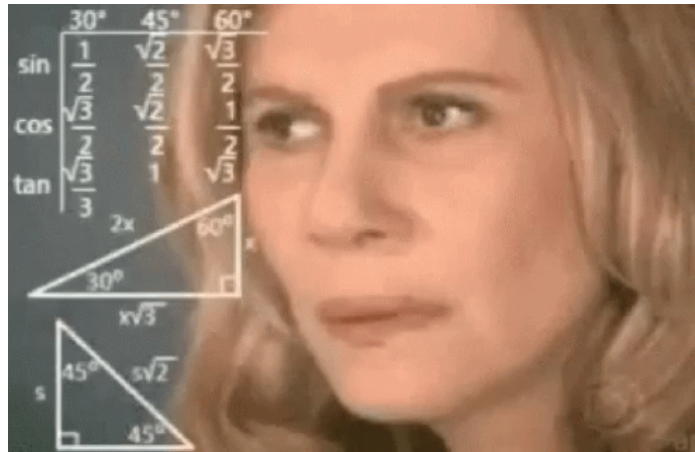
- The core of what happens inside Neural Networks
- We don't handle these ourselves and rarely manually do MatMuls
- It is important to understand the principles





# Matrix Multiplication

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ a_4 & a_5 & a_6 \end{bmatrix} \times \begin{bmatrix} b_1 & b_2 \\ b_3 & b_4 \\ b_5 & b_6 \end{bmatrix} = \begin{bmatrix} c_1 & c_2 \\ c_3 & c_4 \end{bmatrix}$$





# Matrix Multiplication

Let's see an animation.



$$\begin{bmatrix} -1 & 5 & 3 \\ 3 & 7 & 11 \end{bmatrix} \cdot \begin{bmatrix} 2 & 3 \\ -8 & 0 \\ 3 & 3 \end{bmatrix} = \begin{bmatrix} & \\ & \end{bmatrix}$$







# Matrix Multiplication

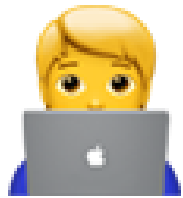
Some rules given a two tensors with shape  $(2 \times 3) * (3 \times 2) = (2 \times 2)$

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ a_4 & a_5 & a_6 \end{bmatrix} \times \begin{bmatrix} b_1 & b_2 \\ b_3 & b_4 \\ b_5 & b_6 \end{bmatrix} = \begin{bmatrix} c_1 & c_2 \\ c_3 & c_4 \end{bmatrix}$$

- Inner dimensions match match.
  - $(2 \times 3) (3 \times 2)$
- Resulting tensor has the shape of the outer:
  - $(2 \times 3) (3 \times 2)$







# Let's Code

*See the website for a link to the Notebooks*





# Reshaping Tensors

*Transposing, Squeezing and Unsqueezing*





# Transposing

- Transposing a tensor flips the rows and columns.
- A tensor with shape (4, 5) becomes shape (5, 4)
- Useful when you want to MatMul two tensors with the same shape.
- In PyTorch you can transpose a tensor with the `.T` method.

```
1 X = torch.rand(4, 8)
2 X_transposed = X.T
3 print(X_transposed.shape)
4 > torch.Size([8, 4])
```





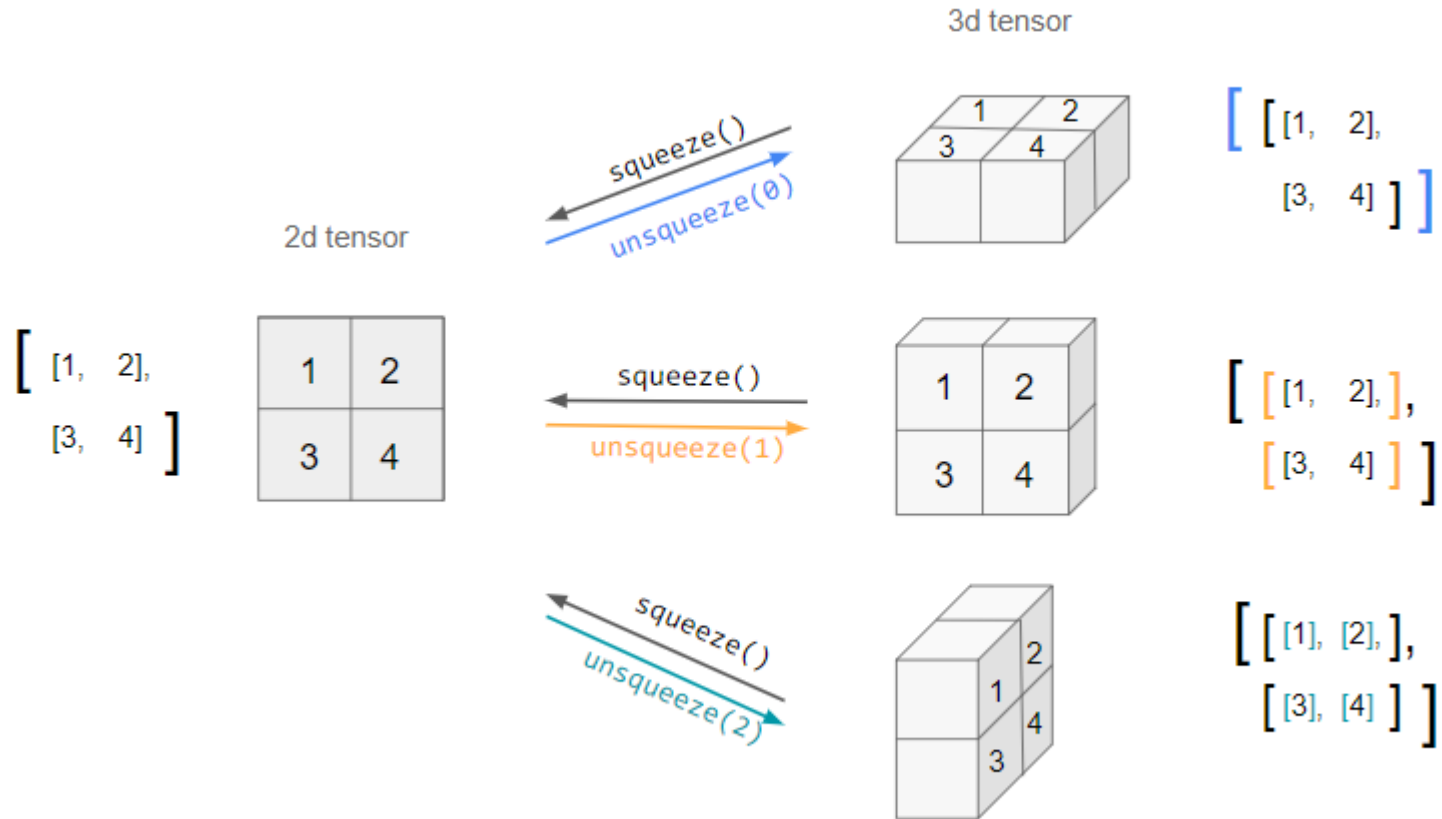
# Squeezing

- Squeezing is the process of removing dimensions from a tensor.
- Removing any 1's (singleton dimensions) from a tensors shape.  $(2, 1, 2)$  becomes  $(2, 2)$
- In PyTorch this can be seen with the removal of brackets [ ]
- This is done with the `.squeeze()` method.





# Squeezing





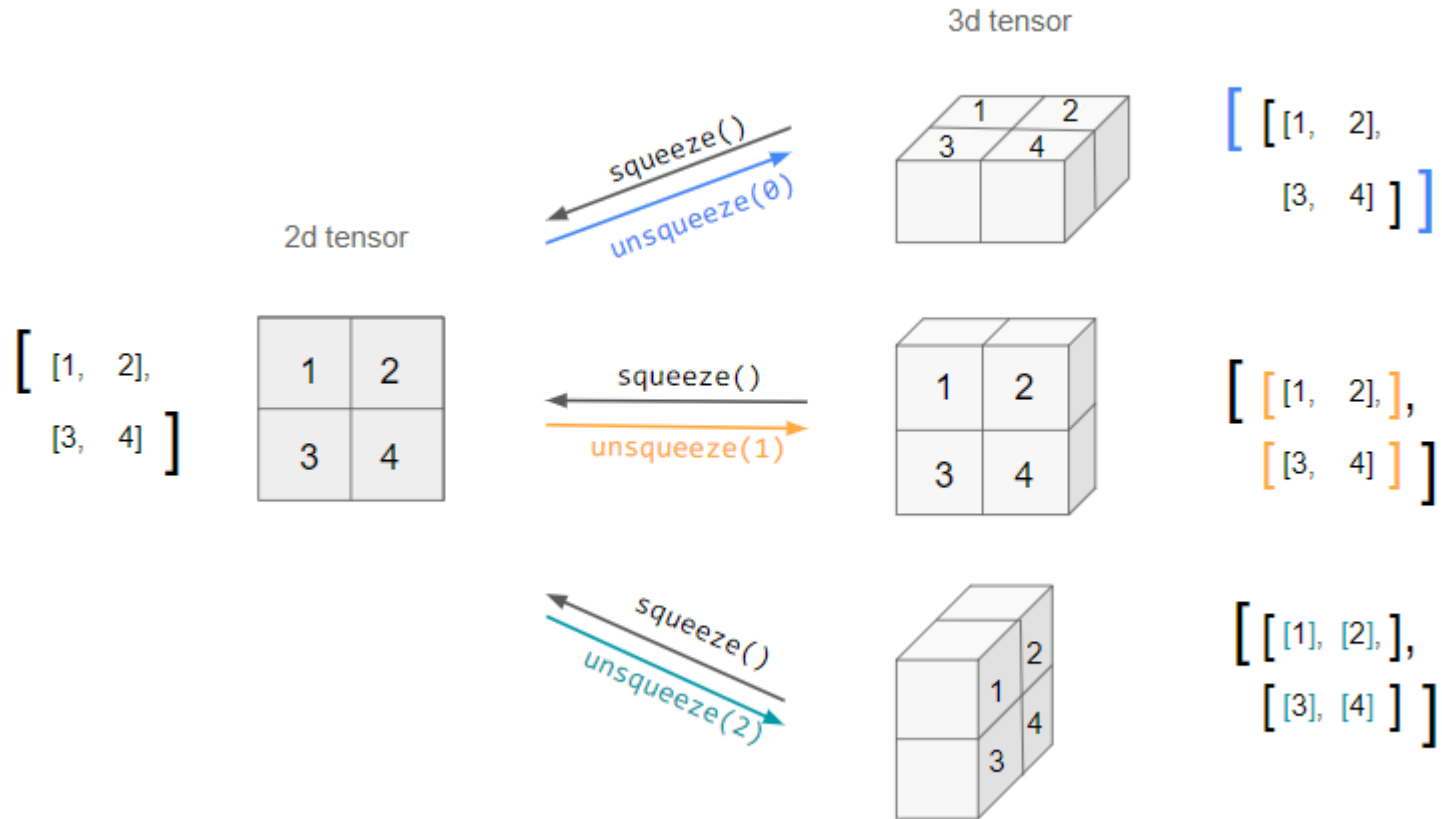
# Unsquizing

- Unsquizing is then the opposite of squizing
- Adding any 1 to a tensors shape, but needs a dimension specified.
- $(2, 2)$  becomes:
  - $(1, 2, 2)$  when we select  $dim=0$
  - $(2, 1, 2)$  when we select  $dim=1$
  - $(2, 2, 1)$  when we select  $dim=2$





# Unsquizing





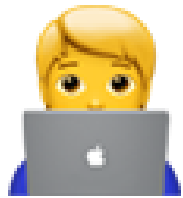
# Unsquizing

- In PyTorch this can be seen with the addition of brackets [ ]
- This is done with the `.unsqueeze(dim)` method.
  - where `dim` would be the index of where you want to dimension to be added.

```
1 X = torch.rand(2, 2)
2 X_unsqueezed = X.unsqueeze(0)
3 print(X_unsqueezed.shape)
4 > torch.Size([1, 2, 2])
```







# Let's Code

*See the website for a link to the Notebooks*



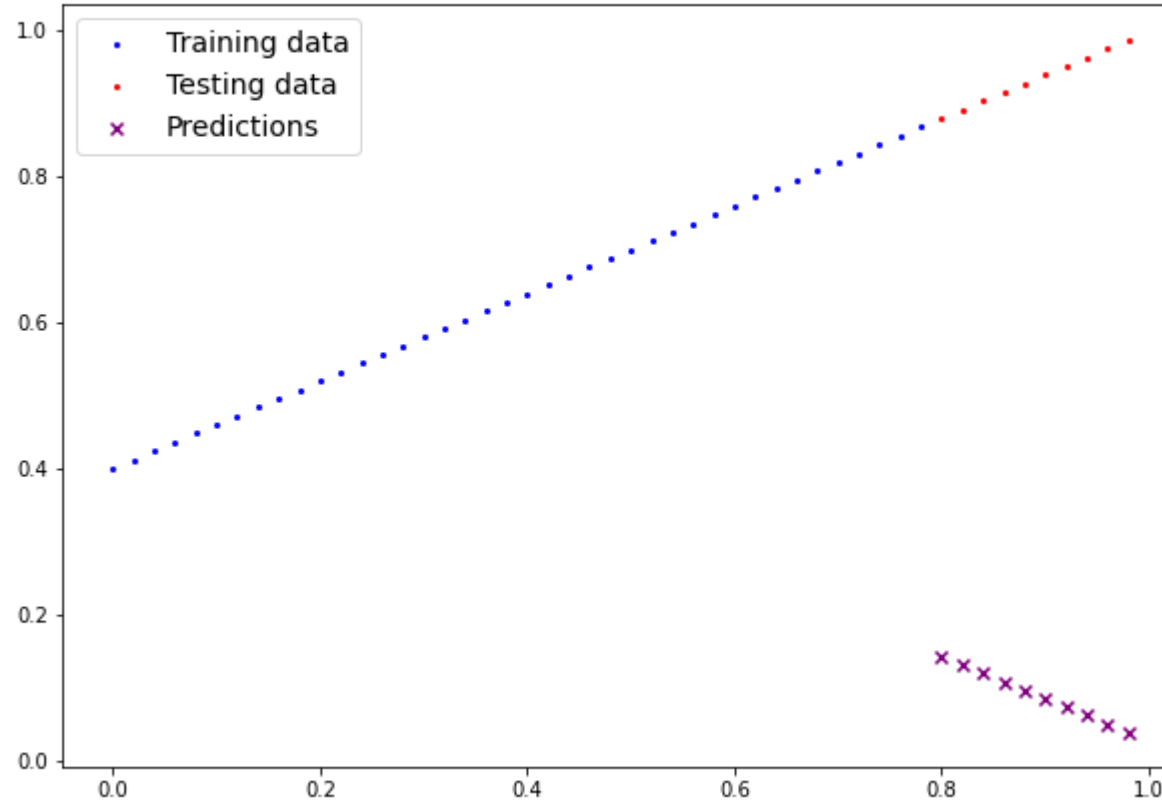


# Round-up





# In two week: Linear Regression



# Works Cited

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